

Eigenvalue problems for some nonlinear perturbations of the Laplace operator

by
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Abstract

The goal of this paper is to prove existence results for some eigenvalue problems in which is involved a class of nonlinear operators which perturb the Laplace operator. Our proofs rely essentially on the Banach fixed point theorem and on a minimization technique.

Key Words: Nonlinear perturbation of the Laplace operator, eigenvalue problem, principal frequency.

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1 Introduction and main results

The study of eigenvalue problems of various differential operators captured an enormous interest in the last decades. A large variety of papers pointed out different phenomena which can occur on the spectrum of certain differential operators. We just remember the recent advances in [3, 4, 5, 7, 8, 9, 10, 11, 12, 15, 16]. The goal of this paper is to point out certain results on an eigenvalue problem in which we perturb the Laplace operator in a sense that will be described later. More exactly, in this paper we are concerned with the study of an eigenvalue problem of the type

$$\begin{cases} -\operatorname{div}(\mathcal{A}(\nabla u)) = \lambda u, & \text{for } x \in \Omega \\ u = 0, & \text{for } x \in \partial\Omega, \end{cases} \quad (1)$$

where $\Omega \subset \mathbf{R}^N$ ($N \geq 3$) is a bounded domain with smooth boundary, $\lambda > 0$ and $\mathcal{A} : \mathbf{R}^N \rightarrow \mathbf{R}^N$ is a function which represents a perturbation of the Laplace operator that will be specified later in the paper.

In the case when $\mathcal{A}(\xi) = \xi$ for all $\xi \in \mathbf{R}^N$ problem (1) goes back to the classical problem

$$\begin{cases} -\Delta u = \lambda u, & \text{for } x \in \Omega \\ u = 0, & \text{for } x \in \partial\Omega. \end{cases} \quad (2)$$

A real number λ is called an *eigenvalue* of problem (2) if there exists $u \in H_0^1(\Omega) \setminus \{0\}$ such that

$$\int_{\Omega} \nabla u \nabla \varphi \, dx = \lambda \int_{\Omega} u \varphi \, dx, \quad \forall \varphi \in H_0^1(\Omega).$$

The function u is called an *eigenfunction* associated with the eigenvalue λ .

It is known (see e.g. Brezis [1], Theorem IX.31) that for problem (2) there exists a nondecreasing sequence of positive eigenvalues $\{\lambda_n\}$ such that $\lambda_n \rightarrow \infty$ as $n \rightarrow \infty$. More exactly, the spectrum of the Laplace operator is *discrete* on bounded domains with smooth boundary. Furthermore, λ_1 is the minimum of the Rayleigh quotient

$$\lambda_1 = \min_{u \in H_0^1(\Omega) \setminus \{0\}} \frac{\int_{\Omega} |\nabla u|^2 \, dx}{\int_{\Omega} u^2 \, dx},$$

and is called *the principal frequency*. The associated eigenfunction u describes the shape of a membrane when it vibrates emitting its gravest tone, cf. Polya and Szego [13]. It is known that λ_1 is simple, i.e. all the associated eigenfunctions u are merely constant multiples of each other (see e.g. Gilbarg and Trudinger [2]). Moreover, the first eigenfunction never changes signs in Ω . On the other hand, higher eigenvalues are not simple (see e.g. Polya and Szego [13]).

This time we study problem (1) when $\operatorname{div}(\mathcal{A}(\nabla u))$ is a perturbation of the Laplace operator. Thus, throughout this paper we assume that \mathcal{A} is of the type

$$\mathcal{A}(\xi) = (\mathcal{A}_1(\xi), \dots, \mathcal{A}_N(\xi)), \quad \forall \xi = (\xi_1, \dots, \xi_N) \in \mathbf{R}^N,$$

with $\mathcal{A}_1, \dots, \mathcal{A}_N : \mathbf{R}^N \rightarrow \mathbf{R}$ and for any $i \in \{1, \dots, N\}$ either $\mathcal{A}_i(\xi) = \cos(\xi_i) + 2\xi_i$ or $\mathcal{A}_i(\xi) = \sin(\xi_i) + 2\xi_i$, for all $\xi = (\xi_1, \dots, \xi_N) \in \mathbf{R}^N$.

Definition 1. We say that $\lambda \in \mathbf{R}$ is an *eigenvalue* of problem (1) if there exists $u \in H_0^1(\Omega) \setminus \{0\}$ such that

$$\int_{\Omega} \mathcal{A}(\nabla u) \nabla \varphi \, dx = \lambda \int_{\Omega} u \varphi \, dx, \quad \forall \varphi \in H_0^1(\Omega).$$

We prove that the operators of the type described above possess a *continuous family* of positive eigenvalues in a right neighborhood of the origin excepting the case when $\mathcal{A}_i(x) = \sin(x_i) + 2x_i$ for all $i \in \{1, \dots, N\}$ and all $x \in \Omega$. However, even in that case we can prove the existence of at least one positive eigenvalue. The main results of our study are given by the following theorems:

Theorem 1. Assume that there exists $i_0 \in \{1, \dots, N\}$ such that $\mathcal{A}_{i_0}(x) = \cos(x_{i_0}) + 2x_{i_0}$ for all $x \in \mathbf{R}^N$. Then any $\lambda \in (0, \lambda_1)$ is an eigenvalue of problem (1), where λ_1 is the first eigenvalue of the Laplace operator.

Theorem 2. Assume that for any $i \in \{1, \dots, N\}$ we have $\mathcal{A}_i(x) = \sin(x_i) + 2x_i$ for all $x \in \mathbf{R}^N$. Then there exists at least a positive eigenvalue λ of problem (1), such that $\lambda \geq \lambda_1$ where λ_1 is the first eigenvalue of the Laplace operator.

Theorem 3. Assume the hypotheses of Theorem 1 are fulfilled. Then there exists at least a positive eigenvalue λ of problem (1), such that $\lambda \geq \lambda_1$ where λ_1 is the first eigenvalue of the Laplace operator.

Throughout this paper we denote by $\langle \cdot, \cdot \rangle$ the scalar product on the Sobolev space $H_0^1(\Omega)$ and by $\|\cdot\|$ the corresponding norm on $H_0^1(\Omega)$, i.e.

$$\langle u, v \rangle = \int_{\Omega} \nabla u \nabla v \, dx, \quad \|u\| = \left(\int_{\Omega} |\nabla u|^2 \, dx \right)^{1/2}.$$

We also denote by $\|\cdot\|_{L^2}$ the norm on the Lebesgue space $L^2(\Omega)$, i.e.

$$\|u\|_{L^2} = \left(\int_{\Omega} u^2 \, dx \right)^{1/2}.$$

2 Proof of Theorem 1

In order to prove Theorem 1 we use a method borrowed from the proof of a nonlinear version of the Lax-Milgram Theorem (see Zeidler [18], Section 2.15). Our proof will use as main tool the Banach fixed point theorem (see Zeidler [18], Section 1.6).

First, we define the operators $a : H_0^1(\Omega) \times H_0^1(\Omega) \rightarrow \mathbf{R}$ by

$$a(u, v) = \int_{\Omega} \mathcal{A}(\nabla u) \nabla v \, dx, \quad \forall u, v \in H_0^1(\Omega)$$

and $b_{\lambda} : H_0^1(\Omega) \times H_0^1(\Omega) \rightarrow \mathbf{R}$ by

$$b_{\lambda}(u, v) = \lambda \int_{\Omega} uv \, dx, \quad \forall u, v \in H_0^1(\Omega).$$

It is enough to show that for any $\lambda \in (0, \lambda_1)$ there exists $u \in H_0^1(\Omega)$ such that

$$a(u, v) = b_{\lambda}(u, v), \quad \forall u, v \in H_0^1(\Omega).$$

We point out certain properties of the operators a respectively b_{λ} .

Proposition 1. The operator a verifies the following properties:

- (i) for any $w \in H_0^1(\Omega)$ the application $v \rightarrow a(w, v)$ is linear and continuous on $H_0^1(\Omega)$;
- (ii) $\|u - v\|^2 \leq a(u, u - v) - a(v, u - v)$, for all $u, v \in H_0^1(\Omega)$;
- (iii) $|a(u, w) - a(v, w)| \leq 3 \cdot \|u - v\| \cdot \|w\|$, for all $u, v \in H_0^1(\Omega)$.

Proof: For any $i \in \{1, \dots, N\}$ we set $\gamma_i(x_i) = \mathcal{A}_i(x) - 2x_i$, for all

$$x = (x_1, \dots, x_N) \in \mathbf{R}^N.$$

(i) We fix $w \in H_0^1(\Omega)$. It is clear that the application $v \rightarrow a(w, v)$ is linear. On the other hand, using Hölder's inequality we have

$$\begin{aligned} |a(w, v)| &= \left| \int_{\Omega} \mathcal{A}(\nabla w) \nabla v \, dx \right| \\ &= \left| \sum_{i=1}^N \int_{\Omega} \gamma_i \left(\frac{\partial w}{\partial x_i} \right) \frac{\partial v}{\partial x_i} \, dx + 2 \int_{\Omega} \nabla w \nabla v \, dx \right| \\ &\leq \sum_{i=1}^N \int_{\Omega} \left| \gamma_i \left(\frac{\partial w}{\partial x_i} \right) \right| \left| \frac{\partial v}{\partial x_i} \right| \, dx + 2 \|w\| \cdot \|v\| \\ &\leq \sum_{i=1}^N \int_{\Omega} \left| \frac{\partial w}{\partial x_i} \right| \, dx + 2 \|w\| \cdot \|v\| \\ &\leq (c + 2 \|w\|) \|v\| \end{aligned}$$

where c is a positive constant. It follows that $v \rightarrow a(w, v)$ is continuous.

(ii) We have

$$\begin{aligned} &a(u, u - v) - a(v, u - v) \\ &= \int_{\Omega} (\mathcal{A}(u) - \mathcal{A}(v)) \nabla(u - v) \, dx \\ &= \sum_{i=1}^N \int_{\Omega} \left(\gamma_i \left(\frac{\partial u}{\partial x_i} \right) - \gamma_i \left(\frac{\partial v}{\partial x_i} \right) \right) \left(\frac{\partial u}{\partial x_i} - \frac{\partial v}{\partial x_i} \right) \, dx + 2 \cdot \|u - v\|^2. \end{aligned}$$

Using the mean value theorem and taking into account that $|\gamma_i'(y)| \leq 1$ for all $y \in \mathbf{R}$ and all $i \in \{1, \dots, N\}$ we deduce that

$$\begin{aligned} a(u, u - v) - a(v, u - v) &= \sum_{i=1}^N \int_{\Omega} \gamma_i'(\theta_i) \left(\frac{\partial u}{\partial x_i} - \frac{\partial v}{\partial x_i} \right)^2 \, dx + 2 \cdot \|u - v\|^2 \\ &\geq -\|u - v\|^2 + 2 \cdot \|u - v\|^2 = \|u - v\|^2 \end{aligned}$$

where $\theta_i(x) = \mu_i(x) \frac{\partial u}{\partial x_i}(x) + (1 - \mu_i(x)) \frac{\partial v}{\partial x_i}(x)$ for all $i \in \{1, \dots, N\}$ and for all $x \in \Omega$ with $\mu_i(x) \in [0, 1]$ for all $i \in \{1, \dots, N\}$ and all $x \in \Omega$.

(iii) Using the same arguments and notations as above we have

$$\begin{aligned}
& |a(u, w) - a(v, w)| \\
&= \left| \sum_{i=1}^N \int_{\Omega} \left(\gamma_i \left(\frac{\partial u}{\partial x_i} \right) - \gamma_i \left(\frac{\partial v}{\partial x_i} \right) \right) \frac{\partial w}{\partial x_i} dx + 2 \int_{\Omega} \nabla(u - v) \nabla w dx \right| \\
&\leq \sum_{i=1}^N \int_{\Omega} |\gamma'_i(\theta_i)| \cdot \left| \frac{\partial u}{\partial x_i} - \frac{\partial v}{\partial x_i} \right| \cdot \left| \frac{\partial w}{\partial x_i} \right| dx + 2 \int_{\Omega} |\nabla(u - v)| \cdot |\nabla w| dx \\
&\leq \sum_{i=1}^N \int_{\Omega} \left| \frac{\partial u}{\partial x_i} - \frac{\partial v}{\partial x_i} \right| \cdot \left| \frac{\partial w}{\partial x_i} \right| dx + 2 \int_{\Omega} |\nabla(u - v)| \cdot |\nabla w| dx \\
&\leq 3 \cdot \|u - v\| \cdot \|w\|.
\end{aligned}$$

The proof of Proposition 1 is complete. \square

Proposition 2. For any $\lambda \in (0, \lambda_1)$ the operator b_λ verifies the following properties:

(i) b_λ is bilinear and continuous on $H_0^1(\Omega) \times H_0^1(\Omega)$;

(ii) $b_\lambda(u, u) \geq 0$ for all $u \in H_0^1(\Omega)$;

(iii) there exists $M > 0$ such that

$$|b_\lambda(u, w) - b_\lambda(v, w)| \leq M \cdot \|u - v\| \cdot \|w\|, \quad \forall u, v, w \in H_0^1(\Omega).$$

Proof: (i) It is clear that b_λ is a bilinear operator on $H_0^1(\Omega) \times H_0^1(\Omega)$. On the other hand, Hölder's inequality and the Sobolev continuous embedding theorem of $H_0^1(\Omega)$ in $L^2(\Omega)$ imply

$$|b_\lambda(u, v)| \leq \lambda \cdot \|u\|_{L^2} \cdot \|v\|_{L^2} \leq c \cdot \|u\| \cdot \|v\|, \quad \forall u, v \in H_0^1(\Omega)$$

where c is a positive constant. That fact shows that b_λ is continuous.

(ii) For any $u \in H_0^1(\Omega)$ we have $b_\lambda(u, u) = \lambda \|u\|_{L^2}^2 \geq 0$.

(iii) Using again Hölder's inequality and the Sobolev continuous embedding theorem of $H_0^1(\Omega)$ in $L^2(\Omega)$ we obtain

$$\begin{aligned}
|b_\lambda(u, w) - b_\lambda(v, w)| &= \lambda \left| \int_{\Omega} (u - v) w dx \right| \\
&\leq \lambda \cdot \|u - v\|_{L^2} \cdot \|w\|_{L^2} \\
&\leq M \cdot \|u - v\| \cdot \|w\|, \quad \forall u, v, w \in H_0^1(\Omega)
\end{aligned}$$

where M is a positive constant. The proof of Proposition 2 is complete. \square

PROOF OF THEOREM 1. Let $\lambda \in (0, \lambda_1)$ be arbitrary but fixed. By Proposition 1 (i) and the Riesz theorem we deduce that for each $u \in H_0^1(\Omega)$ there is an

element called $Au \in H_0^1(\Omega)$ such that

$$a(u, v) = \langle Au, v \rangle = \int_{\Omega} \nabla Au \nabla v \, dx, \quad \forall v \in H_0^1(\Omega).$$

Thus we can define an operator $A : H_0^1(\Omega) \rightarrow H_0^1(\Omega)$. By Proposition 1 (ii) and (iii) it follows that A verifies the properties

$$\|u - v\|^2 \leq \langle Au, u - v \rangle - \langle Av, u - v \rangle, \quad \forall u, v \in H_0^1(\Omega) \quad (3)$$

i.e. A is strongly monotone, and

$$|\langle Au, w \rangle - \langle Av, w \rangle| \leq 3 \cdot \|u - v\| \cdot \|w\|, \quad \forall u, v, w \in H_0^1(\Omega). \quad (4)$$

Relation (4) implies

$$\|Au - Av\| = \sup_{\|w\| \leq 1} |\langle Au - Av, w \rangle| \leq 3 \cdot \|u - v\|, \quad \forall u, v \in H_0^1(\Omega). \quad (5)$$

On the other hand, by Proposition 2 (i) and the Riesz theorem we deduce that for each $u \in H_0^1(\Omega)$ there is an element called $B_\lambda u \in H_0^1(\Omega)$ such that

$$b_\lambda(u, v) = \langle B_\lambda u, v \rangle = \int_{\Omega} \nabla B_\lambda u \nabla v \, dx, \quad \forall v \in H_0^1(\Omega).$$

In this way we can define an operator $B_\lambda : H_0^1(\Omega) \rightarrow H_0^1(\Omega)$. By Proposition 2 and the variational characterization of λ_1 it follows that B_λ is a linear operator which satisfies the properties:

$$\langle B_\lambda u, u - v \rangle - \langle B_\lambda v, u - v \rangle = b_\lambda(u - v, u - v) \leq \frac{\lambda}{\lambda_1} \cdot \|u - v\|^2, \quad \forall u, v \in H_0^1(\Omega) \quad (6)$$

and

$$\begin{aligned} \|B_\lambda u - B_\lambda v\| &= \sup_{\|w\| \leq 1} |\langle B_\lambda u - B_\lambda v, w \rangle| = \\ &= \sup_{\|w\| \leq 1} |b_\lambda(u - v, w)| \leq M \cdot \|u - v\|, \quad \forall u, v \in H_0^1(\Omega). \end{aligned} \quad (7)$$

We define the operator $S : H_0^1(\Omega) \rightarrow H_0^1(\Omega)$ by

$$Su = u - t(Au - B_\lambda u)$$

where $t \in (0, \frac{2(1-\lambda/\lambda_1)}{(3+M)^2})$. The relations (3), (5), (6) and (7) show that for each

$v_1, v_2 \in H_0^1(\Omega)$ the following inequalities hold true

$$\begin{aligned}
& \|Sv_1 - Sv_2\|^2 \\
&= \langle Sv_1 - Sv_2, Sv_1 - Sv_2 \rangle \\
&= \langle (v_1 - v_2) - t(Av_1 - Av_2) + t(B_\lambda v_1 - B_\lambda v_2), (v_1 - v_2) - t(Av_1 - Av_2) + \\
&\quad t(B_\lambda v_1 - B_\lambda v_2) \rangle \\
&= \|v_1 - v_2\|^2 - 2t\langle Av_1 - Av_2, v_1 - v_2 \rangle + 2t\langle B_\lambda v_1 - B_\lambda v_2, v_1 - v_2 \rangle - \\
&\quad 2t^2\langle Av_1 - Av_2, B_\lambda v_1 - B_\lambda v_2 \rangle + t^2\|Av_1 - Av_2\|^2 + t^2\|B_\lambda v_1 - B_\lambda v_2\|^2 \\
&\leq \|v_1 - v_2\|^2 - 2t\|v_1 - v_2\|^2 + \\
&\quad 2t\frac{\lambda}{\lambda_1}\|v_1 - v_2\|^2 + 2t^2\|Av_1 - Av_2\| \cdot \|B_\lambda v_1 - B_\lambda v_2\| + \\
&\quad t^2\|Av_1 - Av_2\|^2 + t^2\|B_\lambda v_1 - B_\lambda v_2\|^2 \\
&\leq \left(1 - 2t\left(1 - \frac{\lambda}{\lambda_1}\right) + 6Mt^2 + 9t^2 + M^2t^2\right) \cdot \|v_1 - v_2\|^2 \\
&= \alpha \cdot \|v_1 - v_2\|^2
\end{aligned}$$

where $\alpha = 1 - 2\left(1 - \frac{\lambda}{\lambda_1}\right)t + (3 + M)^2t^2 \geq 0$. If $t = 0$ or $t = \frac{2(1-\lambda/\lambda_1)}{(3+M)^2}$ then $\alpha = 1$. This implies that $\sqrt{\alpha} < 1$ for all $t \in (0, \frac{2(1-\lambda/\lambda_1)}{(3+M)^2})$.

Therefore,

$$\|Sv_1 - Sv_2\| \leq \sqrt{\alpha} \cdot \|u - v\|, \quad \forall u, v \in H_0^1(\Omega)$$

i.e. S is $\sqrt{\alpha}$ -contractive with $\sqrt{\alpha} < 1$. By the Banach fixed point theorem (see Zeidler [18], Section 1.6) it follows that the problem

$$u = Su$$

has a unique solution $u \in H_0^1(\Omega)$, i.e. the problem

$$Au = B_\lambda u$$

has a unique solution $u \in H_0^1(\Omega)$. It follows that

$$\langle Au, \varphi \rangle = \langle B_\lambda u, \varphi \rangle, \quad \forall \varphi \in H_0^1(\Omega)$$

i.e.

$$\int_{\Omega} \mathcal{A}(\nabla u) \nabla \varphi \, dx = \lambda \int_{\Omega} u \varphi \, dx, \quad \forall \varphi \in H_0^1(\Omega).$$

Finally we remark that $u \neq 0$ since B_λ vanishes in the origin while A does not vanish in the origin. Thus we have proved that any $\lambda \in (0, \lambda_1)$ is an eigenvalue of problem (1). The proof of Theorem 1 is complete. \square

3 Proof of Theorem 2

First, we point out the fact that under the hypotheses of Theorem 2 the conclusion of Theorem 1 does not hold. Indeed, in that case we have $\mathcal{A}(0) = 0$ and thus the non-triviality of the solution obtained by applying the Banach fixed point theorem can not be stated. However, we can prove the existence of a positive eigenvalue of problem (1) under the hypotheses of Theorem 2 using a minimization technique. Such techniques are usually used in finding principal eigenvalues (see e.g. Szulkin-Willem [14]). We remark that the minimization procedure can be also used in order to prove Theorem 3.

We define the functional $I : H_0^1(\Omega) \rightarrow \mathbf{R}$,

$$I(u) = \int_{\Omega} F(\nabla u) \, dx, \quad \forall u \in H_0^1(\Omega)$$

where $F : \mathbf{R}^N \rightarrow \mathbf{R}$ is the function $F(\xi) = \sum_{i=1}^N (-\cos(\xi_i) + \xi_i^2)$, for all $\xi = (\xi_1, \dots, \xi_N) \in \mathbf{R}^N$. It is clear that

$$\frac{\partial F}{\partial x_i}(\xi) = \sin(\xi_i) + 2\xi_i = \mathcal{A}_i(\xi), \quad \forall i \in \{1, \dots, N\} \text{ and } \forall \xi \in \mathbf{R}^N,$$

i.e. $\nabla F(\xi) = \mathcal{A}(\xi)$ for all $\xi \in \mathbf{R}^N$. Thus it is easy to remark that I is of class C^1 on $H_0^1(\Omega)$ with the derivative given by

$$\langle I'(u), v \rangle = \int_{\Omega} \mathcal{A}(\nabla u) \nabla v \, dx, \quad \forall u, v \in H_0^1(\Omega).$$

We consider the minimization problem

(P) minimize $I(u)$ under conditions $u \in H_0^1(\Omega)$ and $\int_{\Omega} u^2 \, dx = 1$.

We point out the fact that problem (P) is well defined. Indeed, for all $u \in H_0^1(\Omega)$ with $\int_{\Omega} u^2 \, dx = 1$ we have

$$I(u) = \sum_{i=1}^N \int_{\Omega} -\cos\left(\frac{\partial u}{\partial x_i}\right) \, dx + \|u\|^2 \geq -N \cdot |\Omega| + \lambda_1 > -\infty \quad (8)$$

where λ_1 is the first eigenvalue of the Laplace operator.

Proposition 3. *The functional I is weakly lower semicontinuous on $H_0^1(\Omega)$.*

Proof: Let (u_n) be a sequence in $H_0^1(\Omega)$ such that u_n converges weakly to u in $H_0^1(\Omega)$. We show that

$$\liminf_{n \rightarrow \infty} I(u_n) \geq I(u).$$

First, we remark that

$$I(u_n) - I(u) = \sum_{i=1}^N \int_{\Omega} \left(-\cos\left(\frac{\partial u_n}{\partial x_i}\right) - \left(-\cos\left(\frac{\partial u}{\partial x_i}\right) \right) \right) \, dx + \|u_n\|^2 - \|u\|^2.$$

Applying the mean-value theorem it follows that

$$I(u_n) - I(u) = \sum_{i=1}^N \int_{\Omega} \sin(w_n^{(i)}) \left(\frac{\partial u_n}{\partial x_i} - \frac{\partial u}{\partial x_i} \right) dx + \|u_n\|^2 - \|u\|^2 \quad (9)$$

where $w_n^{(i)}(x) = \mu_n^{(i)}(x) \frac{\partial u_n}{\partial x_i}(x) + (1 - \mu_n^{(i)}(x)) \frac{\partial u}{\partial x_i}(x)$ for all n , all $i \in \{1, \dots, N\}$ and all $x \in \Omega$ with $\mu_n^{(i)}(x) \in [0, 1]$ for all n , all $i \in \{1, \dots, N\}$ and all $x \in \Omega$.

On the other hand, we have

$$\begin{aligned} & \sum_{i=1}^N \int_{\Omega} \sin(w_n^{(i)}) \left(\frac{\partial u_n}{\partial x_i} - \frac{\partial u}{\partial x_i} \right) dx \\ &= \sum_{i=1}^N \int_{\Omega} \sin \left(\mu_n^{(i)}(x) \left(\frac{\partial u_n}{\partial x_i} - \frac{\partial u}{\partial x_i} \right) + \frac{\partial u}{\partial x_i} \right) \left(\frac{\partial u_n}{\partial x_i} - \frac{\partial u}{\partial x_i} \right) dx \\ &= \sum_{i=1}^N \int_{\Omega} \left[\sin \left(\mu_n^{(i)}(x) \left(\frac{\partial u_n}{\partial x_i} - \frac{\partial u}{\partial x_i} \right) + \frac{\partial u}{\partial x_i} \right) - \sin \left(\frac{\partial u}{\partial x_i} \right) \right] \\ & \quad \left(\frac{\partial u_n}{\partial x_i} - \frac{\partial u}{\partial x_i} \right) dx + \sum_{i=1}^N \int_{\Omega} \sin \left(\frac{\partial u}{\partial x_i} \right) \left(\frac{\partial u_n}{\partial x_i} - \frac{\partial u}{\partial x_i} \right) dx. \end{aligned}$$

Applying again the mean value theorem we get

$$\begin{aligned} & \left| \sum_{i=1}^N \int_{\Omega} \sin(w_n^{(i)}) \left(\frac{\partial u_n}{\partial x_i} - \frac{\partial u}{\partial x_i} \right) dx \right| \\ &= \left| \sum_{i=1}^N \int_{\Omega} \mu_n^{(i)}(x) \cos(\xi_n^{(i)}) \left(\frac{\partial u_n}{\partial x_i} - \frac{\partial u}{\partial x_i} \right)^2 dx + \right. \\ & \quad \left. \sum_{i=1}^N \int_{\Omega} \sin \left(\frac{\partial u}{\partial x_i} \right) \left(\frac{\partial u_n}{\partial x_i} - \frac{\partial u}{\partial x_i} \right) dx \right| \\ &\leq \|u_n - u\|^2 + \left| \sum_{i=1}^N \int_{\Omega} \sin \left(\frac{\partial u}{\partial x_i} \right) \left(\frac{\partial u_n}{\partial x_i} - \frac{\partial u}{\partial x_i} \right) dx \right|. \end{aligned} \quad (10)$$

Relations (9) and (10) imply

$$\begin{aligned} & I(u_n) - I(u) \\ &\geq \|u_n\|^2 - \|u_n - u\|^2 - \|u\|^2 - \left| \sum_{i=1}^N \int_{\Omega} \sin \left(\frac{\partial u}{\partial x_i} \right) \left(\frac{\partial u_n}{\partial x_i} - \frac{\partial u}{\partial x_i} \right) dx \right|. \end{aligned} \quad (11)$$

Since u_n converges weakly to u in the Hilbert space $H_0^1(\Omega)$ using Remark 1.33 on p. 22 in [17] we deduce

$$\lim_{n \rightarrow \infty} (\|u_n\|^2 - \|u_n - u\|^2 - \|u\|^2) = 0 \quad (12)$$

On the other hand, we define the functional $T : H_0^1(\Omega) \rightarrow \mathbf{R}$ by

$$\langle T, \varphi \rangle = \sum_{i=1}^N \int_{\Omega} \sin\left(\frac{\partial u}{\partial x_i}\right) \frac{\partial \varphi}{\partial x_i} dx, \quad \forall \varphi \in H_0^1(\Omega).$$

It is clear that T is linear on $H_0^1(\Omega)$. Using Hölder's inequality we deduce

$$\begin{aligned} |\langle T, \varphi \rangle| &\leq \sum_{i=1}^N \int_{\Omega} \left| \sin\left(\frac{\partial u}{\partial x_i}\right) \right| \left| \frac{\partial \varphi}{\partial x_i} \right| dx \\ &\leq \sum_{i=1}^N \left\| \sin\left(\frac{\partial u}{\partial x_i}\right) \right\|_{L^2} \cdot \left\| \frac{\partial \varphi}{\partial x_i} \right\|_{L^2} \\ &\leq \left(\sum_{i=1}^N \left\| \sin\left(\frac{\partial u}{\partial x_i}\right) \right\|_{L^2}^2 \right)^{1/2} \cdot \left(\sum_{i=1}^N \left\| \frac{\partial \varphi}{\partial x_i} \right\|_{L^2}^2 \right)^{1/2} \\ &\leq \left(\sum_{i=1}^N \left\| \sin\left(\frac{\partial u}{\partial x_i}\right) \right\|_{L^2}^2 \right)^{1/2} \cdot \|\varphi\|, \quad \forall \varphi \in H_0^1(\Omega). \end{aligned}$$

Thus, T is linear and continuous on $H_0^1(\Omega)$. Since u_n converges weakly to u in $H_0^1(\Omega)$ we obtain

$$\lim_{n \rightarrow \infty} \sum_{i=1}^N \int_{\Omega} \sin\left(\frac{\partial u}{\partial x_i}\right) \left(\frac{\partial u_n}{\partial x_i} - \frac{\partial u}{\partial x_i} \right) dx = 0. \quad (13)$$

Relations (11), (12) and (13) imply

$$\liminf_{n \rightarrow \infty} I(u_n) \geq I(u).$$

We conclude that I is weakly lower semicontinuous on $H_0^1(\Omega)$. The proof of Proposition 3 is complete. \square

PROOF OF THEOREM 2. By relation (8) there exists $\Lambda_1 \in \mathbf{R}$ such that

$$\Lambda_1 = \inf_{u \in H_0^1(\Omega), \int_{\Omega} u^2 dx = 1} I(u).$$

There exists (u_n) , a minimizing sequence in $H_0^1(\Omega)$, i.e.

$$I(u_n) \rightarrow \Lambda_1$$

and $\int_{\Omega} u_n^2 dx = 1$ for all n . We point out the fact that (u_n) is bounded in $H_0^1(\Omega)$. Indeed, the above information shows that

$$\begin{aligned} \|u_n\|^2 &= I(u_n) + \sum_{i=1}^n \int_{\Omega} \cos\left(\frac{\partial u_n}{\partial x_i}\right) dx \\ &\leq I(u_n) + N|\Omega| \\ &\leq \Lambda_1 + N|\Omega| + c, \quad \forall n \end{aligned}$$

where c is a positive constant.

The fact that (u_n) is bounded in $H_0^1(\Omega)$ implies that there exists $u \in H_0^1(\Omega)$ such that u_n converges weakly to u in $H_0^1(\Omega)$. Since $H_0^1(\Omega)$ is compactly embedded in $L^2(\Omega)$ we deduce that $\int_{\Omega} u^2 dx = 1$. On the other hand, by Proposition 3 we have

$$\Lambda_1 = \liminf_{n \rightarrow \infty} I(u_n) \geq I(u).$$

Thus we obtain $I(u) = \Lambda_1$, i.e. u is a solution of problem (P).

Let $v \in H_0^1(\Omega)$ be arbitrary but fixed. Then for all ϵ in a suitable neighborhood of the origin the function

$$g(\epsilon) = I\left(\frac{u + \epsilon v}{\|u + \epsilon v\|_{L^2}}\right) = \int_{\Omega} F\left(\frac{\nabla u + \epsilon \nabla v}{\|u + \epsilon v\|_{L^2}}\right) dx$$

is well defined and possesses a minimum in $\epsilon = 0$. Then it is clear that $g'(0) = 0$. A simple computation shows that

$$g'(\epsilon) = \int_{\Omega} \mathcal{A}\left(\frac{\nabla u + \epsilon \nabla v}{\|u + \epsilon v\|_{L^2}}\right) \cdot \frac{\nabla v \cdot \|u + \epsilon v\|_{L^2}^2 - (\nabla u + \epsilon \nabla v) \cdot (\int_{\Omega} uv dx + \epsilon \int_{\Omega} v^2 dx)}{\|u + \epsilon v\|_{L^2}^3} dx$$

Since $\int_{\Omega} u^2 dx = 1$ we get

$$g'(0) = \int_{\Omega} \mathcal{A}(\nabla u) \left(\nabla v - \nabla u \int_{\Omega} uv dx\right) dx$$

and thus

$$\int_{\Omega} \mathcal{A}(\nabla u) \nabla v dx = \lambda \int_{\Omega} uv dx$$

where $\lambda = \int_{\Omega} \mathcal{A}(\nabla u) \nabla u dx \geq \|u\|^2 \geq \lambda_1 \int_{\Omega} u^2 dx = \lambda_1 > 0$. We conclude that $\lambda \geq \lambda_1$ is an eigenvalue for problem (1). The proof of Theorem 2 is complete. \square

4 Final remarks

In this section we point out the fact that our study can be extended to the operators $\mathcal{A} : \mathbf{R}^N \rightarrow \mathbf{R}^N$ of the type

$$\mathcal{A}(\xi) = (\mathcal{A}_1(\xi), \dots, \mathcal{A}_N(\xi)), \quad \forall \xi = (\xi_1, \dots, \xi_N) \in \mathbf{R}^N$$

with $\mathcal{A}_1, \dots, \mathcal{A}_N : \mathbf{R}^N \rightarrow \mathbf{R}$ and $\mathcal{A}_i(\xi) = h_i(\xi_i) + (k+1)\xi_i$ for all $\xi = (\xi_1, \dots, \xi_N) \in \mathbf{R}^N$ and all $i \in \{1, \dots, N\}$, where k is a positive constant and for all $i \in \{1, \dots, N\}$, $h_i : \mathbf{R} \rightarrow \mathbf{R}$ are given functions. Assume that for any $i \in \{1, \dots, N\}$ the function h_i is of class C^1 on \mathbf{R} and admits a bounded primitive $H_i : \mathbf{R} \rightarrow \mathbf{R}$. Moreover, we assume that

$$|h_i(\xi)| \leq k \quad \text{and} \quad |h'_i(\xi)| \leq \min\left\{k, \frac{k+1}{2}\right\}, \quad \forall \xi \in \mathbf{R}, \quad i \in \{1, \dots, N\}.$$

Remark. In the case when $h_i(\xi) = \cos(\xi)$ or $h_i(\xi) = \sin(\xi)$ and $k = 1$ we obtain the operators studied in the above sections. We remark that there exists also other functions h_i which satisfy the above conditions. An example can be $h_i(\xi) = \frac{1}{\alpha+1} \cdot \exp(-|\xi|) \cdot \sin(\alpha \cdot \xi)$, for all $\xi \in \mathbf{R}$, where $\alpha > 0$ and $k = 1$.

In the following we will say that an operator $\mathcal{A} : \mathbf{R}^N \rightarrow \mathbf{R}^N$ is of the type (T) if it verifies the above conditions. In the case of such an operator the same arguments used in the proof of Theorems 1-3 enable us to state the following result:

Theorem 4. (i) Assume \mathcal{A} is an operator of type (T). Then there exists at least a positive eigenvalue λ of problem (1), such that $\lambda \geq \lambda_1$ where λ_1 is the first eigenvalue of the Laplace operator.

(ii) Assume that \mathcal{A} is an operator of type (T) and there exists $i_0 \in \{1, \dots, N\}$ such that h_{i_0} does not vanish in the origin. Then any $\lambda \in (0, \lambda_1)$ is an eigenvalue of problem (1), where λ_1 is the first eigenvalue of the Laplace operator.

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